

A Literature Review on Quantifying Roadside Evolution Using Computer Vision and Deep Learning

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Abstract—This research uses computer vision and deep learning to automate the monitoring and analysis of land use changes in urban or rural areas. It replaces traditional manual methods with image segmentation models that classify satellite or aerial imagery into key land use categories such as residential areas, industrial zones, water bodies, and vegetation. By comparing these categories over time, the system tracks changes such as urban expansion, loss of green spaces, and variations in vegetation health. Using OpenCV, it calculates percentage changes in land use classes, providing a faster, cost-effective, and scalable approach. The findings offer valuable insights for urban planning, environmental management, and sustainable development, enabling data-driven decisions to address modern challenges.

Keywords—Land use monitoring, computer vision, deep learning, image segmentation, urban planning, environmental management, satellite imagery, aerial imagery, OpenCV, urban growth analysis, land use transformation, vegetation monitoring, automated analysis, sustainable development.

INTRODUCTION

As urbanization and environmental changes accelerate globally, monitoring land use transformations in both urban and rural areas has become increasingly critical. Traditional methods for tracking these transformations—such as manual surveys, ground mapping, or satellite data

analysis—are often costly, time-consuming, and labour-intensive. These limitations make it challenging to obtain timely and accurate data that can inform urban planning, environmental management, and sustainable development efforts. In response to these challenges, this research explores the use of computer vision (CV) and deep learning techniques to develop an automated system for analysing and quantifying land use changes over time. This approach not only improves efficiency but also enables a scalable solution that supports dynamic urban and rural area assessment.

Our proposed system leverages the YOLO (You Only Look Once) model, a popular deep learning architecture renowned for its speed and accuracy in object detection tasks. The model is specifically tailored to segment and classify key land use categories such as residential areas, industrial zones, water bodies, and vegetation within satellite or drone imagery. Unlike traditional methods that often require separate models or manual inspection to identify each land type, our YOLO-based approach integrates these categories into a single model, making it more efficient and capable of providing a comprehensive analysis in a single processing step. This unified model significantly reduces the complexity of monitoring tasks and provides a streamlined solution for assessing land use change.

Automated image segmentation with CV and deep learning offers a substantial improvement over manual approaches. Not only does it eliminate the need for

labour-intensive, repetitive tasks, but it also ensures higher consistency and accuracy in data analysis. Manual surveys can often introduce human error and biases, whereas a CV-based approach processes visual data objectively and reliably. Using deep learning to automate land use monitoring also enables faster data processing, which is especially valuable for tracking rapid urban growth, assessing environmental changes, and responding promptly to emerging issues within a locality.

The flexibility of this system is further enhanced by its ability to work with a variety of free and open-source imagery datasets, including satellite and drone-based images. Publicly accessible satellite sources such as Landsat and Sentinel, as well as drone-collected imagery, provide ample visual data that can be used to train and fine-tune the segmentation model. These datasets are readily available and cover diverse geographic and environmental contexts, making it possible to monitor land use changes across different terrains and regions. By utilising accessible imagery, our system offers a cost-effective solution that can be applied to a wide range of urban and rural environments.

Overall, this study presents an innovative approach to land use monitoring that addresses the needs of urban planners, environmental managers, and policymakers. By providing quantifiable insights into changes in residential, industrial, vegetative, and water-covered areas, the system can guide decision-making in urban development, infrastructure planning, and environmental conservation. The potential of this YOLO-based deep learning model to deliver timely, accurate, and actionable data highlights the transformative role of computer vision in advancing sustainable development practices and adapting to the rapid evolution of land use in a modernizing world.

II. RELATED WORK

Railkar et al. [1] provide foundational insights into how convolutional neural networks (CNNs) combined with transfer learning can achieve highly accurate object detection with limited annotated data. Their research is particularly significant for applications like ours where comprehensive labeled datasets of urban road imagery are scarce. By employing transfer learning, models can leverage pre-existing knowledge to adapt efficiently to new tasks such as detecting road boundaries and land use categories, which improves training speed and reduces resource requirements. Their emphasis on real-time performance resonates strongly with our project's objective to deliver rapid, actionable insights that can aid

urban planners and traffic authorities in timely decision-making.

The advances in image segmentation reviewed by Minaee et al. [2] have been pivotal in transforming how complex urban scenes are analyzed. Their examination of architectures such as Fully Convolutional Networks (FCNs), U-Net, and Mask R-CNN illustrates the evolution from pixel-level classification to instance-level segmentation, which is essential for precisely outlining road features and adjacent land use. Their work underscores the necessity of balancing segmentation accuracy with computational efficiency—a challenge central to our implementation, especially considering potential deployment on resource-constrained edge devices. The ability to segment fine-grained features like roadside vegetation and encroachments depends heavily on these advanced architectures, which provide the backbone for our land use classification models.

Text extraction within urban environments, as explored by Jeeva et al. [3], highlights the capabilities of modern OCR tools such as EasyOCR to accurately recognize multilingual and complex textual data embedded in real-world scenes. Although our project's primary focus lies in structural and environmental monitoring, incorporating such OCR functionalities can enrich our system by automating the extraction of road sign information, regulatory markers, and other textual cues. This integration could significantly enhance the contextual awareness of our models, providing urban planners with more comprehensive data for compliance verification and infrastructure management.

In their study, Liu et al. [4] develop a lightweight yet highly accurate YOLO-based model tailored for detecting illegal constructions in urban settings. Their optimization techniques—reducing model size and computational load while maintaining detection precision—directly inform our choice of lightweight architectures suitable for real-time operation on platforms such as the NVIDIA Jetson Nano. Such efficiency is crucial for field deployment where computational resources and energy consumption are limited but timely, accurate detection remains critical to identifying unauthorized developments and enforcing zoning laws.

The Segment Anything Model (SAM) presented by Kirillov et al. [5] introduces a revolutionary approach to segmentation by providing a promptable, task-agnostic framework capable of zero-shot generalization. While our current models are specialized for road and vegetation detection, SAM's demonstrated flexibility opens avenues for rapid adaptation to new urban monitoring challenges

without extensive retraining. This adaptability could significantly reduce development cycles and enable our system to address diverse scenarios—from emergency response mapping to dynamic urban growth analysis—without the need for large annotated datasets.

OpenCV remains a cornerstone of image processing pipelines in computer vision research, as highlighted in [6]. Its comprehensive functions for preprocessing—such as color space conversions, morphological operations, and contour detection—are indispensable for preparing raw images for deep learning inference. Efficient preprocessing ensures that noise, lighting variations, and other artifacts do not degrade segmentation quality. The extensive use of OpenCV in our pipeline allows for reliable boundary detection and region analysis, supporting the precise quantification of land use categories.

Comparative analyses of real-time object detection frameworks [7] emphasize the strengths of architectures like YOLO, SSD, and Faster R-CNN, particularly their ability to perform well in dynamic, resource-constrained environments. YOLO's single-stage detection paradigm enables high-speed inference while maintaining robust accuracy, making it well-suited to our use case where rapid processing of video streams is required. Its hierarchical feature extraction supports recognition of overlapping objects—a frequent challenge in complex urban landscapes where vegetation, vehicles, and infrastructure coexist closely.

Recent enhancements to YOLO architectures, such as those introduced by Talib and Al-Noori [8] with YOLOv8-CAB, incorporate convolutional block attention mechanisms and integrate instance segmentation capabilities. These advancements refine feature extraction and enhance contextual awareness, enabling improved detection of small, overlapping, or occluded objects. Our models benefit from these techniques, as they allow us to more reliably detect fine-scale features like clustered roadside vegetation or illegal constructions obscured by urban clutter, which are often missed by simpler detectors. The work by Sharma et al. [9] details a CNN-driven system for real-time road infrastructure monitoring that automatically detects lane markers, road boundaries, and other critical features from video data. Their research provides a proof of concept for how automated deep learning systems can replace laborious manual inspections and deliver immediate insights into road conditions and structural changes. This aligns closely with our objective to provide urban authorities with timely information to enhance safety and compliance, particularly in fast-growing urban areas.

Singh et al. [10] further advance this concept by utilizing continuous video analysis to detect lane shifts and boundary changes in real time. Their system highlights the benefits of integrating multiple temporal data streams, reinforcing our approach of comparing images across time to identify gradual or sudden changes in road geometry and land use. This temporal dimension is crucial for understanding urban growth dynamics and enabling proactive maintenance and planning.

Drone-based monitoring presents unique technical challenges, particularly regarding maintaining consistent altitude for accurate spatial analysis. Zhu et al. [11] emphasize the importance of stable drone flight heights and adaptive detection algorithms to account for complex urban backgrounds and perspective changes. Their findings support our operational decision to maintain drone flights at a fixed height of 50 meters to ensure uniform image scale and quality, which significantly improves detection accuracy and temporal consistency.

Mujtaba and Jalal [12] combine semantic segmentation with DeepSort tracking to perform real-time drone-based traffic surveillance, demonstrating the power of coupling detection with temporal tracking. Their methodology inspires our incorporation of temporal change detection, enabling the system to track land use evolution and identify critical transformations over time rather than isolated snapshots.

Zhang et al. [13] apply deep learning techniques to segment complex urban backgrounds from drone imagery for bridge structural monitoring. Although focusing on structural health, their approaches to overcoming challenges posed by visual clutter, lighting variability, and occlusions have informed our preprocessing and segmentation pipeline, ensuring robustness in diverse urban scenes.

Environmental monitoring studies such as those by Halder et al. [14] focus on urban heat islands and the effects of land use changes on microclimates using remote sensing and geospatial data. Their research highlights the environmental significance of monitoring vegetation and urban sprawl, which is central to our project's aim of supporting sustainable urban growth through accurate land use quantification.

Vancutsem et al. [15] present long-term satellite-based monitoring of forest cover changes in tropical regions. Their methodical approach to temporal change detection informs our framework for analyzing multi-temporal imagery to capture trends in urban expansion, vegetation loss, and land reclassification.

Pal et al. [16] provide a comprehensive overview of deep learning techniques for multi-object detection and

tracking, underscoring the importance of real-time capabilities in dynamic environments. Their insights support our integration of CNN-based tracking mechanisms to maintain continuity in detection across frames, which is critical for reducing false positives and improving reliability.

Abdul Kadhar and Anand [17] discuss practical image processing strategies with OpenCV, emphasizing filtering and edge detection techniques that are vital for preparing data before deep learning inference. Their work enhances our understanding of how to optimize preprocessing to maximize segmentation accuracy.

Deshpande et al. [18] use deep learning to detect deforestation and reforestation zones from satellite imagery, showcasing the applicability of AI for environmental monitoring. Their success in identifying subtle vegetation changes reinforces the feasibility of our vegetation detection model as a tool for environmental management.

Srivastava and Ahmed [19] propose a deep learning-based change detection method for monitoring deforestation, successfully capturing incremental land cover shifts over time. Their approach closely parallels our temporal comparison framework, which is designed to detect critical shifts in urban green spaces and built environments.

Finally, Das and Angadi [20] employ remote sensing and GIS to analyze urban growth and land use change on a micro level, demonstrating the transformative impact of automated, data-driven monitoring tools for urban planning. Their findings underscore the necessity of systems like ours, which leverage deep learning for comprehensive, real-time urban infrastructure and environmental monitoring.

III- CONCLUSION

The *Land Use Monitoring and Quantitative Analysis Using Deep Learning* project highlights the powerful potential of computer vision and deep learning in advancing urban planning and land management. By employing a YOLO-based segmentation model, this system enables precise and automated analysis of multiple land use categories, including residential, industrial, water bodies, and vegetation. This approach, which uses pixel-based segmentation to quantify changes in land composition, eliminates the need for manual tracking, providing a fast and efficient alternative to traditional methods of monitoring land use transformations over time. A major strength of the system lies in its ability to track land use changes over different time periods, allowing

urban planners and environmental agencies to detect and quantify shifts, such as urban expansion, reductions in green spaces, or reclassification of land use types. By analysing temporal data, the system identifies critical areas where significant environmental or structural changes have occurred, providing data-driven insights that support sustainable growth and regulatory compliance. The transition from manual surveys to this automated approach not only minimises human error but also greatly accelerates the monitoring process, which is essential for effectively managing dynamic urban and rural environments.

Beyond urban planning, this project has broad applicability, with potential benefits for government agencies, environmental organisations, and municipal authorities. The system can assist in tasks like tracking urban sprawl, monitoring deforestation, and ensuring adherence to environmental guidelines. Integrating additional real-time data, such as weather information, could further expand its capabilities. Extending its application to rural and developing areas would address infrastructure challenges and promote sustainable growth, making this project a valuable model for resource management and responsible land use on a global scale.

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